ACCURATE TIME/FREQUENCY TRANSFER METHOD USING BI-DIRECTIONAL WDM TRANSMISSION

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Abstract

An accurate time transfer method is proposed using bi-directional wavelength division multiplexing (WDM) signal transmission along a single optical fiber. This method will be used in digital telecommunication networks and yield a time synchronization accuracy of better than 1 ns for long transmission lines over several tens of kilometers. The method can accurately measure the difference in delay between two wavelength signals caused by the chromatic dispersion of the fiber in conventional simple bi-directional dual-wavelength frequency transfer methods. We describe the characteristics of this difference in delay and then show that the accuracy of the delay measurement can be obtained below 0.1 ns by transmitting 156 Mb/s time reference signals of 1.31 μ m and 1.55 μ m along a 50 km fiber using the proposed method. The sub-nanosecond delay measurement using the simple bi-directional dual-wavelength transmission along a 100 km fiber with a wavelength spacing of 1 nm in the 1.55 μ m range is also shown.

INTRODUCTION

In digital telecommunication networks, a reference frequency is already being distributed to network nodes in order to synchronize digital switching and multiplexing equipment. If the transmission delay is compensated for by measuring the round-trip path delay using the outgoing and incoming paths, accurate time transfer over long distances will be achieved. The proposed method will yield a time synchronization accuracy of better than 1 ns for long transmission lines over several tens of kilometers. This is useful for operating a distribution network, for locating faults, and in several network time services.

Accuracy in time transfer is determined by the accuracy to which the propagation delay is measured. Since the round-trip path is comprised of paired physically-independent fibers in conventional communication systems^[1], the delay measurement accuracy is limited by the asymmetry of the fiber length. A delay-measuring system using simple bi-directional dual-wavelength transmission along a single fiber^[2] eliminates fiber-length asymmetry, but it incurs error due to the chromatic dispersion of the fiber.

This paper proposes a novel delay-measuring system using bi-directional WDM transmission along a single optical fiber, which can eliminate the error caused by fiber dispersion. The effects

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Form Approved OMB No. 0704-0188 from the difference in delay between the two wavelength signals and the variations are described. The 1.31 μ m and 1.55 μ m signal transmissions along a 50 km fiber are tested and the feasibility of sub-nanosecond time transfer using the proposed method is confirmed. The bi-directional dual-wavelength transmission along a 100 km fiber is also shown, with a wavelength spacing of 1 nm in the 1.55 μ m range. In such a close wavelength transmission system, measuring the sub-nanosecond delay is possible using a simple bi-directional dual-wavelength transmission method (i.e., not using the proposed method).

DELAY MEASURING METHOD

Simple bi-directional dual-wavelength optical transmission for transferring time signals is shown in Figure 1. The master and slave nodes are connected with a single optical fiber and wavelength division multiplexers/demultiplexers. The reference time signals are generated by the reference clock installed in the master node and transmitted from the master to the slave node using λ_1 wavelength light. This λ_1 light is modulated using a digital data stream which includes time signals. The feedback time signals are transferred from the slave to the master node using λ_2 wavelength light. The time interval counter continuously measures the round-trip delay, τ_{sum} , which is the sum of λ_1 propagation delay, τ_1 , and λ_2 delay, τ_2 . The λ_1 propagation delay is estimated as half of τ_{sum} in this scheme. The delay information is sent to the slave node. In this node, the reference time signal derived from the λ_1 light is advanced by electrical phase compensation techniques according to the received delay information.

In this method, the delay measurement error is due to the difference in delay between two wavelength signals, which is caused by the chromatic dispersion of the optical fiber. The proposed delay measurement scheme, presented in Figure 2, compensates for the error due to this fiber dispersion. The reference time signals are always transmitted from the master to the slave using the λ_1 wavelength light. The two 1x2 optical switches change the transfer direction of the λ_2 wavelength light which transfers the probe time signals. When λ_2 signals are transferred from the slave to the master, the time interval counter (TI₁) measures the round-trip signal delay, τ_{sum} . The difference in delay, τ_{diff} , equals $\tau_2 - \tau_i 1$, which can be measured by transferring the λ_2 signals from the master to the slave in the same direction as the λ_1 signals. The λ_1 propagation delay can be accurately determined from the following relationship by measuring both the sum and difference terms.

$$\tau_1 = (\tau_{sum} - \tau_{diss})/2 \tag{1}$$

The optical fiber delays, tau_1 and τ_2 , vary with changes in the environment, especially temperature. Hence, both τ_{sum} and τ_{diff} must be measured repeatedly. The measurement interval required to accurately transfer time depends on the characteristics of the variations in τ_1 and τ_2 . They are discussed in the following section.

EFFECT OF DISPERSION

The difference in delay between two wavelength signals is caused by the difference in the group refractive index between the two wavelengths. The chromatic dispersion, D, is the wavelength variation coefficient of the group refractive index and is illustrated in Figure 3. The characteristic parameters of the dispersion are zero-dispersion wavelength, λ_0 , and the dispersion slope at zero-dispersion wavelength, S_0 . The hatched area shown in Figure 3 expresses the difference in delay between two wavelengths, λ_1 and λ_2 .

We consider here the difference in delay, τ_{diff} , and its variation, $\Delta \tau_{diff}$. This variation, $\Delta \tau_{diff}$, is caused by the difference in the change of the fiber dispersion characteristics with temperature between two wavelength signals. Assuming that S_0 is constant against temperature change in the range from λ_1 to λ_2 and that the zero-dispersion wavelength is only shifted by temperature change, τ_{diff} and $\Delta \tau_{diff}$ with temperature are

$$\tau_{diff} = \frac{1}{2} S_O \cdot ((\lambda_2 - \lambda_0)^2 - (\lambda_1 - \lambda_0)62) \cdot L , \qquad (2)$$

$$\Delta \tau_{diff} = S_O \cdot (\lambda_1 - \lambda_2) \cdot \frac{d\lambda_0}{dT} \cdot L. \tag{3}$$

where L, ΔT , and $d\lambda_0/dT$ denote the fiber length, temperature change, and the temperature dependence of zero-dispersion wavelength, respectively.

The normal single mode fiber (SMF) has a zero-dispersion wavelength around 1310 nm. The dispersion shifted fiber (DSF) has a λ_0 around 1550 nm and is optimized for transmission in the 1550 nm wavelength region. A typical value of the dispersion slope is about +0.07 ps/nm²/km. It is reported that the temperature dependence of the zero-dispersion wavelength, $d\lambda_0/dT$, is about +0.03 nm/°C^[3]. Figure 4 shows the difference in delay per unit fiber length, τ_{diff}/L , as a function of the wavelength difference $\Delta\lambda_0(=\lambda_1-\lambda_2)$ for three different zero-dispersion wavelength fibers. In this calculation, the above parameters and $\lambda_1=1550$ nm were used. The zero-dispersion wavelength of 1310 nm denotes the system using the SMF. The $\lambda_0=1550$ nm and $\lambda_0=1600$ nm are the best and worst cases using the 1.55 μ m DSF, respectively, because the zero-dispersion wavelength of the DSF is specified in the region from 1500 to 1600 nm^[4].

As shown in Figure 4, τ_{diff}/L becomes 2.0 ns/km in the system using 1550 nm and 1310 nm as dual-wavelength signals, where $\lambda_0 = 1550$ nm. For example, the τ_{diff} becomes 100 ns where L = 50 km and it must be compensated for by using our proposed scheme described in the above section for ensuring sub-nanosecond time transfer. Where $\Delta T = 40^{\circ}C$, the $\Delta \tau_{diff}$ becomes 1.0 ns, thus, τ_{diff} must be measured frequently according to the temperature change by changing the direction of the λ_2 signals in the proposed method.

If two close wavelength signals around 1550 nm are used, the difference in delay and its variation become small. For example, where $\lambda_0 = 1600$ nm, $\Delta \lambda = 1$ nm, L = 100 km, and $\Delta T = 40^{\circ}C$, τ_{diff} and $\Delta \tau_{diff}$ are 350 ps and 8.4 ps, respectively. If these values can be ignored, an accurate time transfer will be achieved using a simple bi-directional dual-wavelength time transfer scheme in which two wavelength signals are close. The system using close wavelength

signals within the 1.55 μ m band has several advantages compared to the 1.31 and 1.55 μ m WDM systems: the fiber span can be wider, higher bit-rate signals can be transmitted, and the amount of short-term jitter is expected to be smaller. Recently, many wavelength multiplexing devices such as the arrayed waveguide grating^[5] and the fiber grating filter^[6] have been developed for the 1.55 μ m multi-wavelength division multiplexing system. Therefore, such close wavelength multiplexing and demultiplexing can be easily performed.

EXPERIMENTAL RESULTS

1.31 μ m + 1.55 μ m WDM Transmission

Two 155.52 Mb/s timing reference signals were transmitted bi-directionally along a 50 km 1.55 μ m dispersion shifted fiber (DSF). The DSF had a loss of 0.2 dB/km and a zero dispersion at the 1556 nm wavelength. Fabry-Perot multi-mode laser diodes (FP-LDs) operating at 1548 nm and 1315 nm were used as the λ_1 and λ_2 light sources with the respective output power of -0.4 dBm and +1.8 dBm. Both FP-LDs were directly modulated by 155.52 Mb/s digital signals that included time signals of one pulse per second. The details of the digital signals including time signals were presented in our previous report^[7]. Nominal sensitivity of the optical receivers was -36 dBm at 1550 nm and -37 dBm at 1310 nm. Wavelength-selective couplers and low/high wavelength pass filters were used as wavelength division multiplexers/demultiplexers, and total isolation exceeded 60 dB. To change the direction of the λ_2 signals, we manually changed the fiber connections instead of using optical switches.

Error-free transmission was confirmed in both bi-directional and uni-directional transmission of the λ_1 and λ_2 signals. The bare fiber, wound on bobbins, was set in a temperaturecontrolled chamber and its temperature was varied. The τ_{sum} and τ_{diff} were measured using time interval counters (Stanford Research Systems; model SR620). Due to the fact that both master and slave were set in the same laboratory, true values of τ_1 and τ_2 could be directly measured. Under uni-directional transmission conditions, the τ_1 , τ_2 , their difference, τ_{diff} , and the chamber temperature are plotted in Figure 5. The short-term jitter appearing in the τ_{diff} data is estimated to be mainly due to the electrical circuit used to derive the time signals from the 156 Mb/s signals and the resolution of the time interval counters. The variation of τ_1 or τ_2 was about 74 ns for a temperature change of 40°C. The thermal coefficient of the bare-fiber delay, 37 ps/°C/km, obtained from the above results, agrees with the previous reported results [8]. The difference in delay, τ_{diff} , was 113.6 ns at 25°C and the variation of au_{diff} was about 1.2 ns in this experiment. Under the our experimental conditions in which $\lambda_1 = 1548$ nm, $\lambda_2 = 1315$ nm, $\lambda_0 = 1556$ nm, $\Delta T = 40^{\circ}C$, and L = 50 km, τ_{diff} is 102 ns and $\Delta \tau_{diff}$ is 0.98 ns from equations (2) and (3). These calculated values agree with the experimental results. The difference in delay and its variation under these conditions cannot be ignored for sub-nanosecond time transfer and must be measured and compensated for by using the proposed method.

The measured values of τ_1 , $\tau_{sum}/2$ in the bi-directional transmission and the $\tau_{diff}/2$ measured in the uni-directional transmission are plotted against temperature in Figure 6. The error in determining τ_1 , which equals the difference between τ_1 and the value obtained from equation

(1), is also plotted. The measured value of τ_1 agrees with the delay determined from τ_{sum} and τ_{diff} within about 0.1 ns over the entire temperature range. This result shows that subnanosecond time transfer is possible using the proposed method in the 1.31 μ m and 1.55 μ m WDM system.

WDM Within 1.55 μ m Band Transmission

Distributed feedback (DFB) lasers emitting +3 dBm of optical power at 1547 and 1546 nm were used as λ_1 and λ_2 light sources. Two bit-rate signals of 155.52 Mb/s and 2.48832 Gb/s, including reference time signals, were tested and were used to directly modulate both DFB-LDs. The sensitivity of the optical receivers was -36 dBm for 156 Mb/s signals and -32 dBm for the 2.488 Gb/s signals. The arrayed waveguide gratings, which have 16 channels with a wavelength spacing of 1 nm in the 1.55 μ m band, were used as wavelength division multiplexers/demultiplexers^[9]. The insertion loss was about 7 dB and the crosstalk with other wavelengths was below -30 dB. We demonstrated both 156 Mb/s bi-directional transmission through a 100 km DSF and 2.488 Gb/s bi-directional transmission through a 75 km DSF while altering the temperature range of the bare DSF wound on bobbins. The DSF had a zero dispersion at the 1561 nm wavelength. The variation of independently measured delay τ_1 , τ_2 , and their difference, τ_{diff} , for the 156 Mb/s and 2.488 Gb/s transmissions are plotted with fiber temperature in Figure 7 and Figure 8, respectively.

From equation (2), τ_{diff} of 100 km and 75 km transmissions are +100 ps and +76 ps under the experimental conditions. The experimentally measured τ_{diff} in Figure 7 and Figure 8 were about +0.2 ns and 0.0 ns, respectively. These values agree with the theoretical values within about 0.1 ns. The difference between the experimental and theoretical values is estimated to be caused by the resolution of the time interval counter. Figures 7(b) and 8(b) show the filtered difference in delay, τ_{diff} , with a time constant of 100 s. The filtered τ_{diff} in Figure 7(b) and Figure 8(b) varied within 100 ps and 50 ps, respectively. The theoretical value of $\Delta \tau_{diff}$ due to the temperature change is below 10 ps and it does not appear in Figure 7(b) and Figure 8(b). These results show that the sub-nanosecond delay can be measured using a simple bi-directional transmission in such a close wavelength transmission within the 1.55 μ m range.

The square root of the Time Variance^{10, 11}, $\sigma_x(\tau)$, of the τ_{diff} , is plotted in Figure 9. The error of the time interval counter (model SR620) is also plotted. The error was measured using the following scheme: the time signal used in the above experiment was split; one was input into the start channel of the counter, and the other was input into the stop channel through a several-meter-long coaxial cable as the proper delay. The $\sigma_x(\tau)$ in the averaging time region, t<100 s, was proportional to $\tau^{-1/2}$, which presented white noise phase modulation (PM). In this short term region, the variation of the τ_{diff} is estimated to include both the jitter due to the electrical circuit used to derive the time signals and the error of the counter. In particular, the result of the 2.488 Gb/s transmission experiment almost coincided with $\sqrt{2}$ times the value of the counter error. This agreement shows the accuracy of the delay measurement in the 2.488 Gb/s transmission in the region, t<100 s, was almost solely restricted by the error of the counter, because the noise was characterized by white noise PM and the tdiff was the

difference between two values, τ_1 and τ_2 , which were obtained by two independent counters. In the region of t>100 s, $\sigma_x(\tau)$ was proportional to τ^0 and the variations were characterized by flicker PM. The flicker noises of both the 156 Mb/s and 2.488 Gb/s transmissions were larger than the counter error in the region where t>1000 s. The causes of these noises are not clear.

CONCLUSION

An accurate time transfer method using bi-directional WDM signal transmission was proposed. The 1.31 μ m and 1.55 μ m signal transmission along a 50 km fiber was tested and the feasibility of sub-nanosecond time transfer using the proposed method was shown. We also demonstrated the bi-directional dual-wavelength transmission along a 100 km fiber with a wavelength spacing of 1 nm in the 1.55 μ m range. In such a close wavelength transmission system, the sub-nanosecond delay can be measured using a simple bi-directional dual-wavelength transmission method. These results show that the optical transmission fibers over several tens of kilometers have the capability of time synchronization accuracy of better than 1 ns.

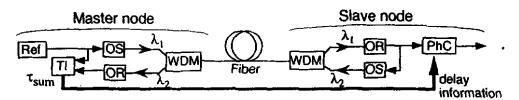
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Ref: Reference time generator, PhC: Phase compensator

OS: Optical sender, OR: Optical receiver,

WDM: Wavelength division multiplexer / demultiplexer

TI: Time interval counter

Fig. 1 Time transfer method using simple bi-directional dual-wavelength transmission. The delay information is actually transmitted with reference time signals including the $\lambda 1$ light.

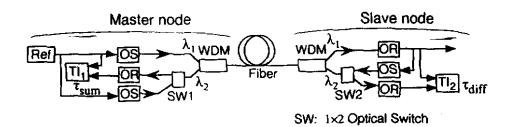


Fig. 2 Proposed delay measurement scheme.

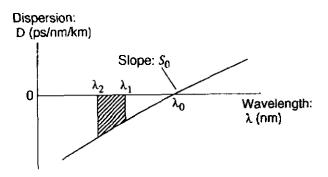


Fig. 3 Chromatic dispersion of optical fiber and its characteristic parameters. The hatched area shows the difference in delay between two wavelengths, λ_1 and λ_2 .

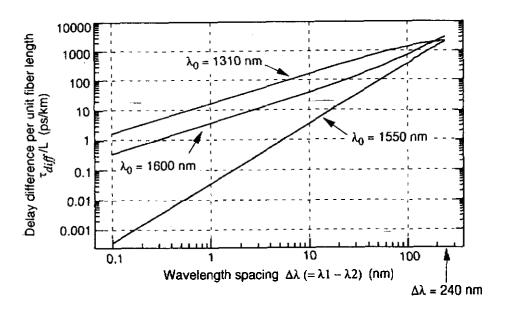


Fig. 4 Delay difference per unit fiber length between two wavelength signals, where the zero dispersion wavelength λ_0 = 1550 nm and the dispersion slope S_0 = +0.07 ps/nm²/km.

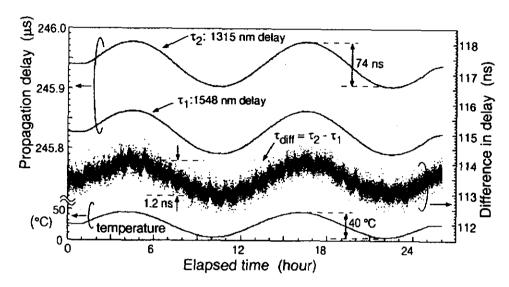


Fig. 5 Measured variations of propagation delay and the difference in delay with temperature change.

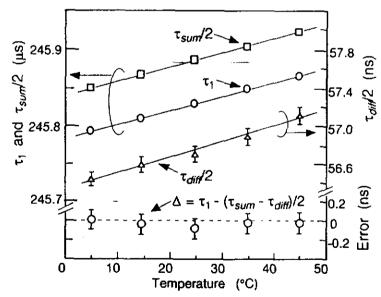
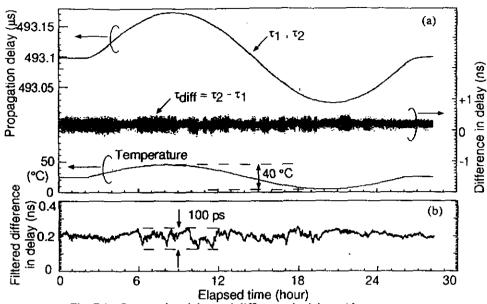


Fig. 6 Measured τ_1 , $\tau_{sum}/2$, $\tau_{diff}/2$, and the error in determining delay, Δ , with temperature.



Elapsed time (hour)
Fig. 7 (a) Propagation delay and difference in delay with temperature.
(b) Filtered difference in delay with time constant of 100 s.

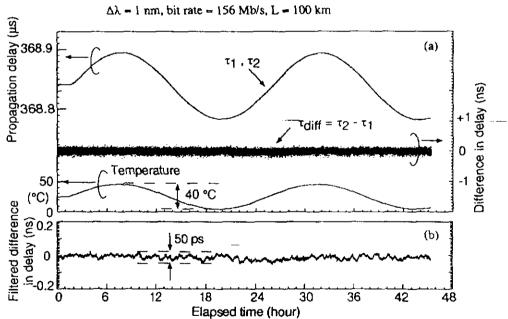


Fig. 8 (a), (b) same as above in conditions of: $\Delta\lambda = 1$ nm, bit rate = 2.488 Gb/s, L = 75 km

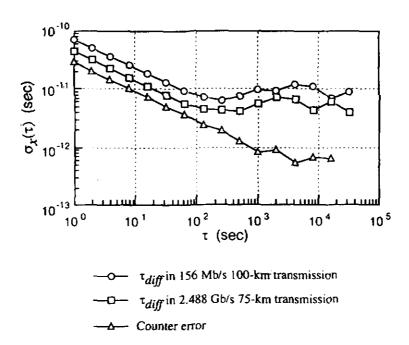


Fig. 9 The square root of Time Variance [11],[12] of τ_{diff} compared with the measurement error of the counter.

Questions and Answers

DAVID ALLAN (ALLAN'S TIME): If this were extended to longer paths, 1000 kilometers, what would you expect the accuracy to be? Is this extendable to, say, 1000 kilometers?

ATSUSHI IMAOKA (NTT): It depends on the range.

DAVID ALLAN (ALLAN'S TIME): Okay, so 1000 kilometers, what would you expect the error to be for it?

ATSUSHI IMAOKA' (NTT): About 10 nanoseconds.